xGFabric: Coupling Sensor Networks and HPC Facilities with 5G Wireless Networks for Real-Time Digital Agriculture

Ryan Hartung (rhartung@nd.edu) University of Notre Dame - http://ccl.cse.nd.edu/

Abstract

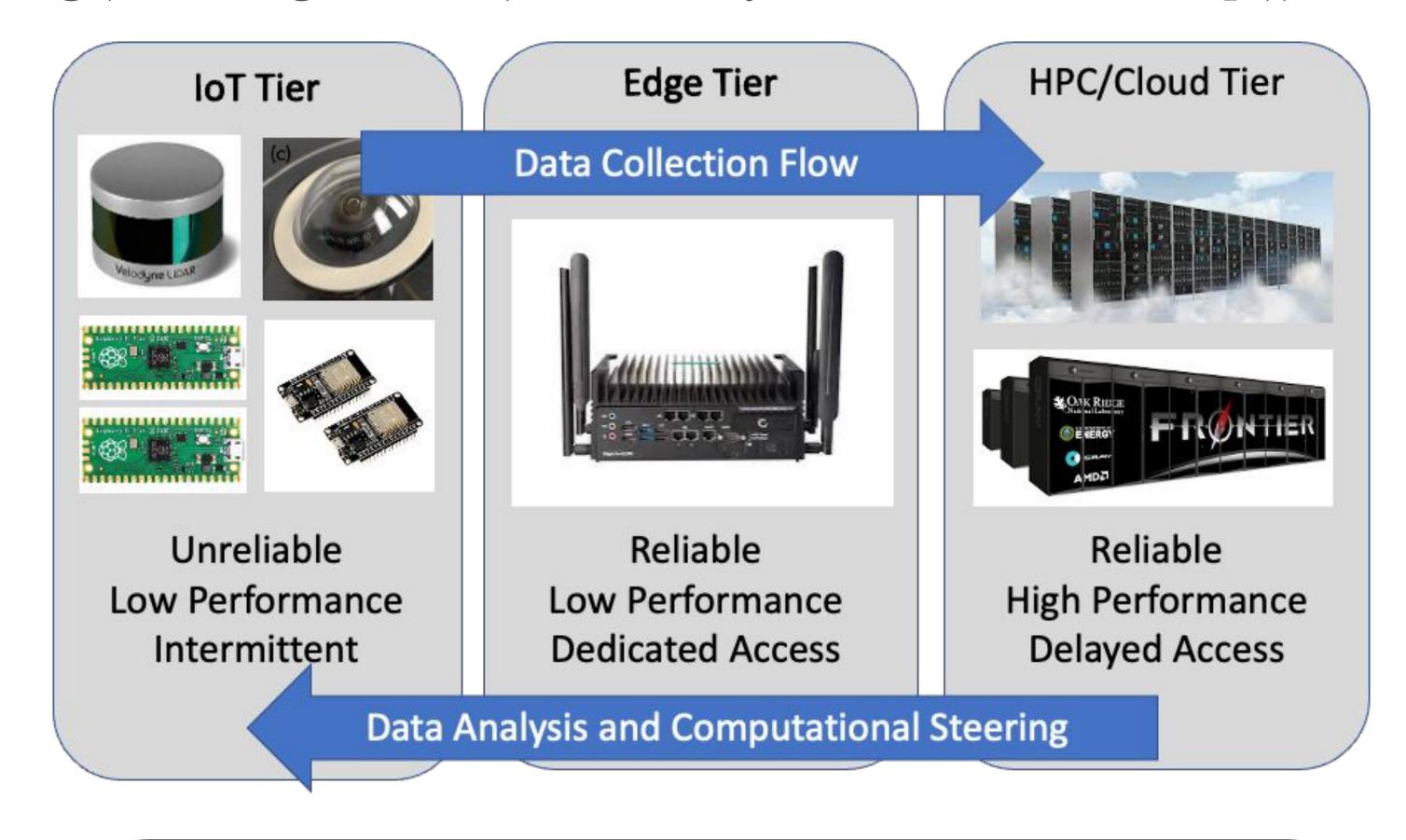
Our objective is to design and evaluate an end-to-end, multi-scale, adaptive system—xGFabric—that unifies leadership-class HPC resources with instruments, and actuators through a computational and storage network. xGFabric leverages 5G/6G technologies to integrate computing, storage, sensing, and actuation across scales using new abstractions, programming models, and middleware. Rather than integrating disparate technologies, we study xGFabric as a cohesive platform with integrated HPC support and distributed workflow management. Advanced wireless digital agriculture serves as our science driver, with prototypes validated on field testbeds at the University of Nebraska-Lincoln and the University of California. Building on our prior research in 5G/6G, IoT, and multi-messenger astronomy, we will develop sensor virtualization for network slicing and release a full-stack, multiscale platform as open-source artifacts.

Tools

6G RAN Wireless Radio Access Network
CSPOT Serverless Platform of Things in C
Laminar Distributed Dataflow Framework

RADICAL Workflow Toolkit

OpenFOAM Computational Fluid Dynamics Simulator

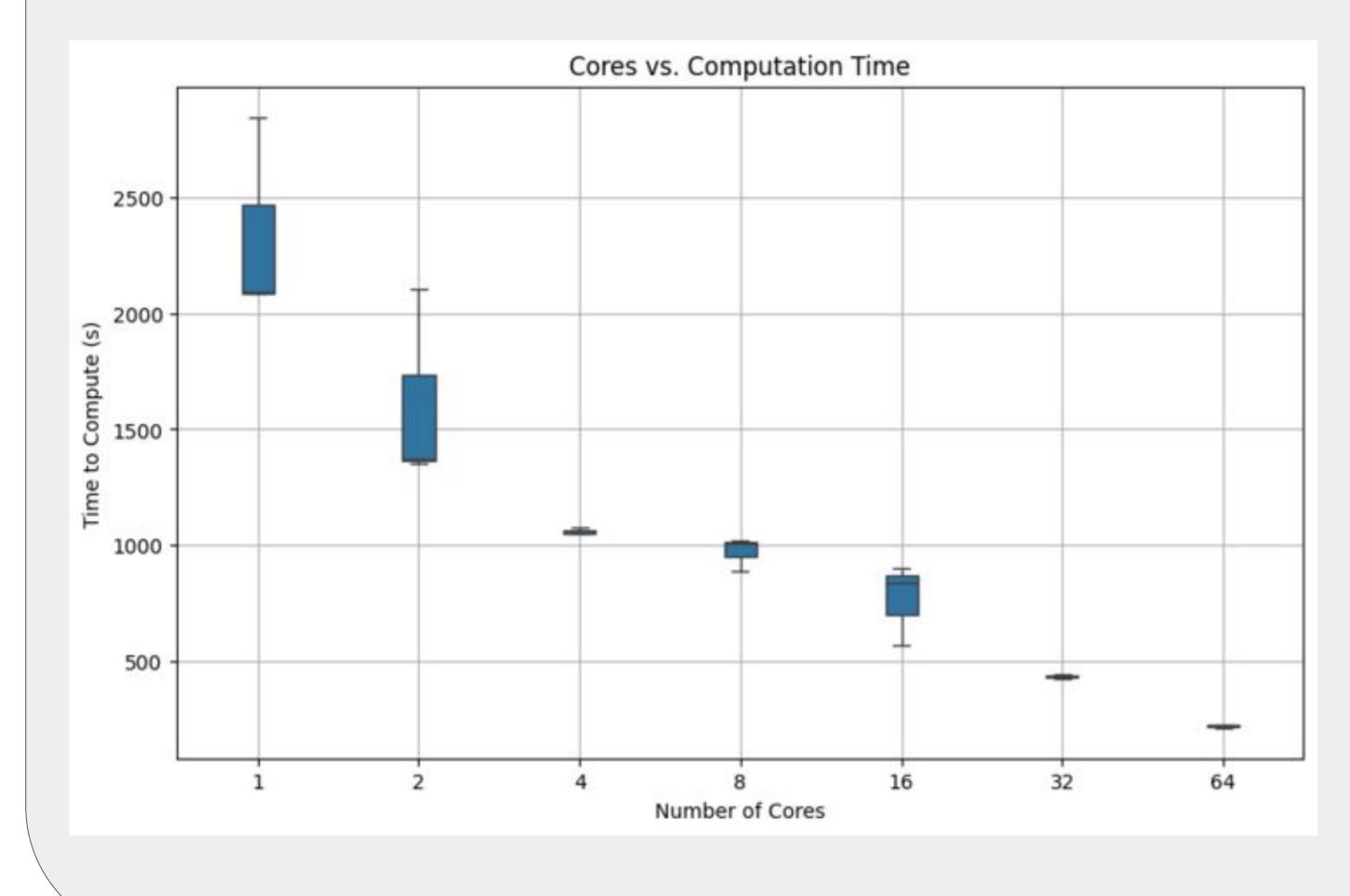


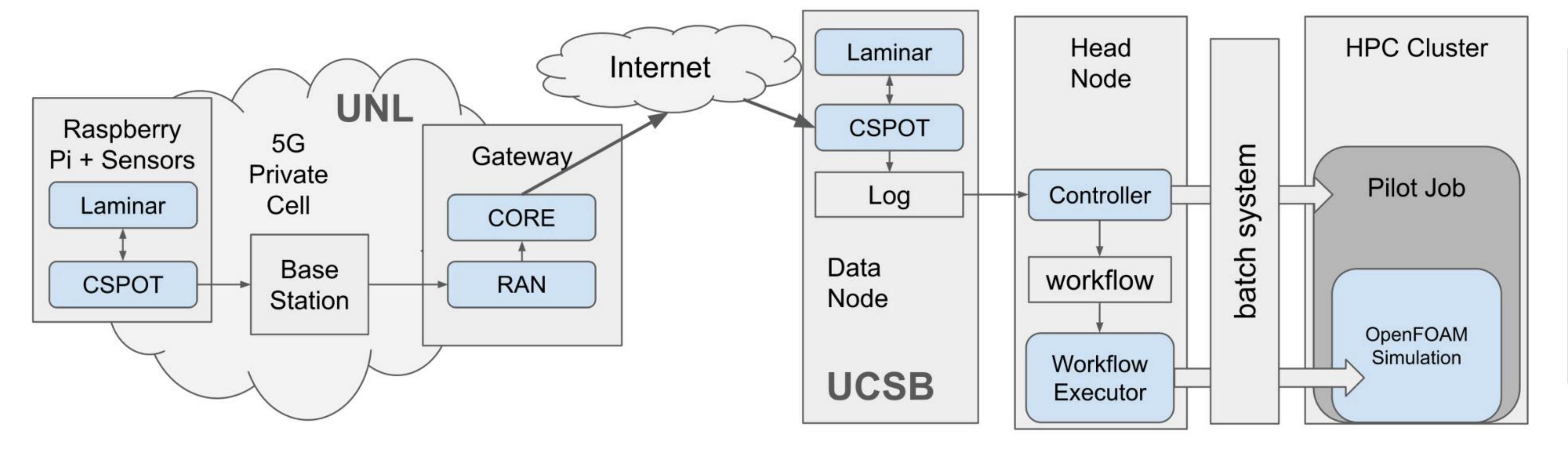
Implementation

The system begins with several sensors planted in the field at UNL collecting weather data. The data is logged to Raspberry Pis via Laminar. Laminar appends data to append-only log files and triggers event-based computations. The Raspberry Pis transmit their data privately over 5G networks to the base station via CSPOT. CSPOT manages secure namespaces for reliable, private data transmissions. The data is then transmitted to UCSB via CSPOT over a 6G RAN and logged with Laminar. Finally, a controller on an HPC head node monitoring the UCSB log file triggers a workflow, which submits an OpenFOAM job to run on the cluster. OpenFOAM simulates the farm using the near real-time data.

Results

Established a working end-to-end prototype that enables near real-time simulation for agriculture. The system's portability has been validated across multiple university's research-class HPC clusters including Notre Stampede3, and Purdue ANVIL. Dame, Texas Comprehensive performance evaluation and scalability testing are currently underway, with detailed results forthcoming. This work establishes unified digital-physical fabric that tightly integrates advanced wireless networks, sensor data, and leadership-class HPC resources to improve crop management and resource applications efficiency extending beyond with agriculture.





Acknowledgements

On behalf of the RADICAL team: Liubov Kurafeeva, Alan Subedi, Ryan Hartung, Avhishek Biswas, Shantenu Jha, Ozgur Kilic, Chandra Krintz, Andre Merzky, Douglas Thain, Mehmet Can Vuran, Rich Wolski.

This work was supported by DOE Grant DE-SC0025541



